

A Tool to Optimize VOC Removal During Absorption and Stripping

Eugénio C. Ferreira
University of Minho (Portugal)

Romualdo Salcedo
University of Porto (Portugal)

Spreadsheet analysis offers a simpler and less costly alternative to simulators and algebraic tools

Practicing engineers routinely use modular simulators and algebraic tools to perform rigorous process optimizations. These complex tools, however, can have a significant learning curve. Meanwhile, spreadsheet programs are becoming a ubiquitous tool for performing calculations for many chemical process operations [1-4]. In this article, we show how the Solver feature of the Microsoft Excel spreadsheet program can be used to optimize a fairly complex system. In this case, the specific goal was to optimize the design of a gas-absorption tower paired with a solvent-recovery stripper for the continuous recovery of organic solvents (VOCs) from a contaminated stream. Two examples are given, with and without environmental emission constraints. The results show that Excel Solver can converge on local optima for these complex systems, as long as proper care is taken during the solution procedure.

Equations and constraints

With the widespread availability of powerful "what if" spreadsheet programs with optimization capabilities (such as Excel), many engineers and students can easily use these tools to solve a typical simulation or optimization problem. It is important to establish the extent to which these tools can solve demanding optimization problems.

The optimization problem discussed in detail here deals with the concepts of process synthesis, heat integration and solvent recovery, and details can be found in Umeda [5], and Umeda and Ichikawa [6]. The problem as discussed here has been adapted from these authors; Silverberg [7] shows that this process is widely in use.

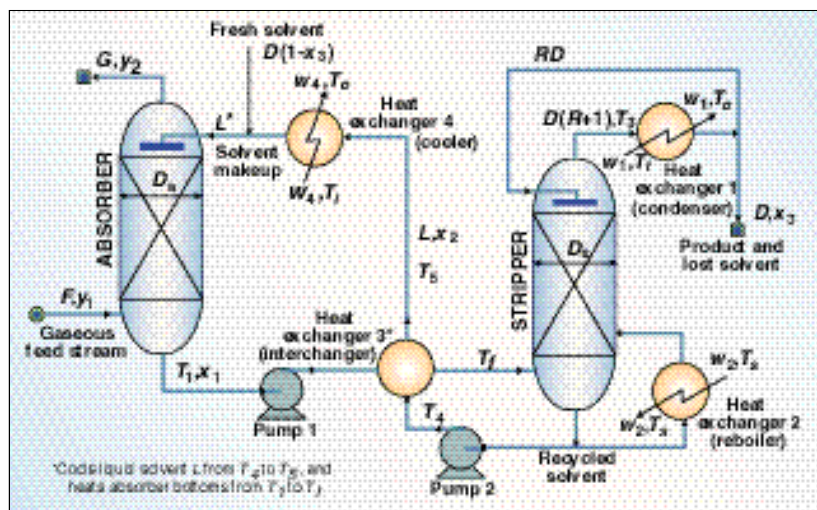


FIGURE 1. The continuous, steady-state process for solvent extraction and recovery shown here is the subject of this optimization study. All symbols are defined with appropriate units in Figure 2, and are computed by the equations in Table 1 or Table 3

Figure 1 shows the continuous and steady-state process under study here. It consists of a packed absorber column, a plate-tower stripper and integrated heat recovery. The gaseous stream F , with mole fraction y_1 of a contaminant to be recovered or removed is fed to the absorber, where a solvent, with flowrate L , is counter-currently enriched in the solute.

The extraction solvent is stripped in a plate tower, and the solute in the overhead vapors is condensed for recovery or further disposal. The cooled solvent is returned to the absorber, where fresh solvent is added to replace losses in the overhead vapors.

The entire set of equality constraints is given in Table 1 (for definitions of the symbols in these well-known design equations, refer to Table 3 and Figure 1, and to standard textbooks). Each equation is set to zero, as is the convention with spreadsheet optimization. The absorber diameter

(Equation f_9) is computed so that the vapor velocity is 75% of the flooding velocity. Estimate the stripper diameter (Equation f_{23}) by dividing the vapor load (defined in Equation 1)

$$V_v = \frac{Q_2}{AM_L} \frac{22.4T_1}{273.2} \quad (1)$$

by the superficial vapor velocity, as calculated by the Souders-Brown equation [8]

$$V_M = K \sqrt{\frac{P_1 - P_2}{P_2}} \quad (2)$$

where K is an empirical constant, and Q_2 equals the heating duty of the reboiler (defined by Equation f_{32}). The Fenske-Underwood equations (Equations f_{24} - f_{25}) are used to compute the minimum number of plates and the minimum reflux ratio. The number of plates (Equations f_{26} - f_{27}) is computed from the Eduljee approximation to Gilliland's graphical method [8].

This is an economic optimization, so

TABLE 1. PROCESS DESIGN EQUATIONS

| TABLE 1. PROCESS DESIGN EQUATIONS | |
|---|---|
| $f_1 = F - G - D x_3 = C$ | ABSORBER |
| $f_2 = F y_1 + L x_2 - (L + D) x_1 - G y_2 = 0$ | STRIPPER & HEAT EXCHANGERS |
| $f_3 = N_{og} - \frac{1}{1 - \frac{HG}{PL}} \ln \left[\left(1 - \frac{HG}{PL} \right) \left(\frac{y_1 - \frac{H}{P} x_2}{y_2 - \frac{H}{P} x_1} \right) + \frac{HG}{PL} \right] = 0$ | $f_{21} = (L + D) x_1 - L x_2 - D x_3 = 0$ |
| $f_4 = H_{og} - H_g - \frac{HG H_1}{PL} = 0$ | $f_{22} = (L + D) c_p T_f + Q_2 - D c_p T_3 - L c_p T_4 - Q_1 = 0$ |
| $f_5 = H_g - \alpha \left(\frac{FM_g}{A_o} \right)^{\beta} \sqrt{Sc_g} / \left(\frac{(L + D) M_1}{A_o} \right)^{\gamma} = 0$ | $f_{23} = \frac{D_i^2}{4} - \frac{22.4 Q_2 T_4}{273.2 \times 3,600 M_1 K_1 \left(\frac{P_1 - P_g}{P_g} \right) / P_g} = 0$ |
| $f_6 = H_f - \left(\frac{(L + D) M_1}{A_o \alpha} \right)^{\delta} \phi \sqrt{Sc_1} = 0$ | $f_{24} = R_m - \frac{1}{\alpha - 1} \left[\frac{x_3}{x_1} - \alpha \frac{(1 - x_3)}{(1 - x_1)} \right] = 0$ |
| $f_7 = A_o - \frac{D_o^2}{4} = 0$ | $f_{25} = N_m - \ln \left[\frac{x_3}{(1 - x_3)} \frac{(1 - x_2)}{x_2} \right] / \ln \alpha = 0$ |
| $f_8 = D_o - \sqrt{\frac{4GM_g}{0.75 \omega G_f 3,600}} = 0$ | $f_{26} = N_m - \frac{(N_m + X)}{(1 - X)} = 0$ |
| $f_9 = \log_{10} \left[G_f^2 \left(\frac{\rho_p}{z} \right) \left(\frac{1}{\rho_p \rho_l} \right) \left(\frac{\sigma}{\sigma_g} \right)^{0.2} \right] - 1.74 \left(\frac{LM_1}{GM_g} \right)^{0.25} \left(\frac{PL}{\rho_g} \right)^{-0.125} = C$ | $f_{27} = X - 0.75 \left[1 - \left(\frac{R - R_m}{R + 1} \right)^{0.5668} \right] = 0$ |
| $f_{11} = HP_1 - K_{p1}(L + D)N = C$ | PUMP NO. 1 |
| $f_{12} = HP_2 - K_{p2}Z = C$ | PUMP NO. 2 |
| $f_{13} = Q_4 - L c_p (T_5 - T_1) = C$ | HEAT EXCHANGER NO. 4 |
| $f_{14} = Q_4 - W_4 c_{pw} (T_2 - T_1) = 0$ | $f_{31} = c_{fm1} - \frac{(T_3 - T_o) - (T_3 - T_i)}{\ln \left(\frac{T_3 - T_o}{T_3 - T_i} \right)} = C$ |
| $f_{15} = Q_4 - U_4 A_4 c_{fm4} = 0$ | $f_{32} = Q_2 - W_2 \lambda_w = 0$ |
| $f_{16} = c_{fm4} - \frac{(T_5 - T_o) - (T_1 - T_i)}{\ln \frac{T_5 - T_o}{T_1 - T_i}} = 0$ | $f_{33} = Q_2 - U_2 A_2 c_{fm2} = 0$ |
| $f_{17} = Q_2 - (L + D) c_p (T_f - T_1) = 0$ | HEAT EXCHANGER NO. 3 |
| $f_{18} = Q_3 - L c_p (T_4 - T_5) = 0$ | $f_{34} = c_{fm2} - \frac{(T_4 - T_d)}{\ln \left(\frac{T_4 - T_d}{T_4 - T_d} \right)} = 0$ |
| $f_{19} = Q_3 - U_3 A_3 c_{fm3} = 0$ | $f_{35} = x_2 e^{\left(\frac{A_1 - B}{T_1 + T_u} \right)} + (1 - x_2) e^{\left(\frac{A_1 - B}{T_1 + T_u} \right)} - P = 0$ |
| $f_{20} = c_{fm3} - \frac{(T_1 - T_5) - (T_1 - T_d)}{\ln \frac{T_1 - T_5}{T_1 - T_d}} = 0$ | $f_{36} = \frac{P x_2}{e^{\left(\frac{A_1 - B}{T_1 + T_u} \right)}} + \frac{P(1 - x_2)}{e^{\left(\frac{A_1 - B}{T_1 + T_u} \right)}} - 1 = 0$ |
| | $f_{37} = T_f - T_2 - (q - 1) \frac{\lambda}{c_p} = 0$ |
| | $f_{38} = x_1 e^{\left(\frac{A_1 - B}{T_1 + T_u} \right)} + (1 - x_1) e^{\left(\frac{A_1 - B}{T_1 + T_u} \right)} - P = 0$ |
| | $f_{39} = x_2^* - \frac{L x_2}{L + D(1 - x_3)} = 0$ |
| | MAKEUP |
| | $f_{40} = L - D(1 - x_3) - L = 0$ |

the objective is to maximize the profit, which is the difference between revenue from the sale of recovered VOCs, and annual capital and operating costs of the system:

$$F_{obj} = P_p D M_1 x_3 - C_g F M_g + C_i D (1 - x_3) M_1 + C_u (w_1 + w_4) + C_s w_2 + C_e (HP_1 + HP_2) + Inv F_c \quad (3)$$

where investment costs (the last symbol in Equation 3) are given by:

$$Inv = C_z Z D_a^{1.0} + C_n N D_s^{1.085} + C_o (A_1^{0.556} + A_2^{0.556} + A_3^{0.556} + A_4^{0.556}) + C_{hp} (HP_1^{0.3} + HP_2^{0.3}) \quad (4)$$

The problem is subject to the 40 equality constraints shown in Table 1, as well as to the following process inequality constraints:

$$L < 300 \text{ Kg-mole/h} \quad (5)$$

(maximum flowrate)

$$R < 20 \quad (6)$$

(maximum reflux in stripper)

Thus, this problem, as formulated, has 45 independent (unknown) variables and 40 equations, with a total of 5 degrees of freedom.

(Continues on p. 96)

TABLE 2. SERIAL SOLUTION PROCEDURE WITH {N, W₄, T₄, T₂ AND A₁} AS DECISION VARIABLES

Equation(Variable) $f_{36}(T_3), f_{14}(Q_4), f_{34}(\Delta T_{im2}), f_{35}(x_2), f_{25}(N_m), f_{26}(X), f_{31}(\Delta T_{im1}), f_{30}(Q_1), f_{29}(W_1), f_{38}(x_1), f_{24}(R_m), f_{27}(R), f_{28}(D), f_1(G), f_{21}(L), f_2(Y_2), f_{11}(HP_1), f_{13}(T_5), f_{16}(\Delta T_{im4}), f_{15}(A_4), f_{18}(Q_3), f_{17}(T_f), f_{20}(\Delta T_{im3}), f_{19}(A_3), f_{22}(Q_2), f_{23}(D_3), f_{32}(W_2), f_{33}(A_2), f_{37}(q), f_{39}(x_2^*), f_{40}(L^*), f_3(N_{og}), f_{10}(G_f), f_8(D_a), f_6(A_a), f_5(H_g), f_6(H_1), f_4(H_{og}), f_7(Z), f_{12}(HP_2)$

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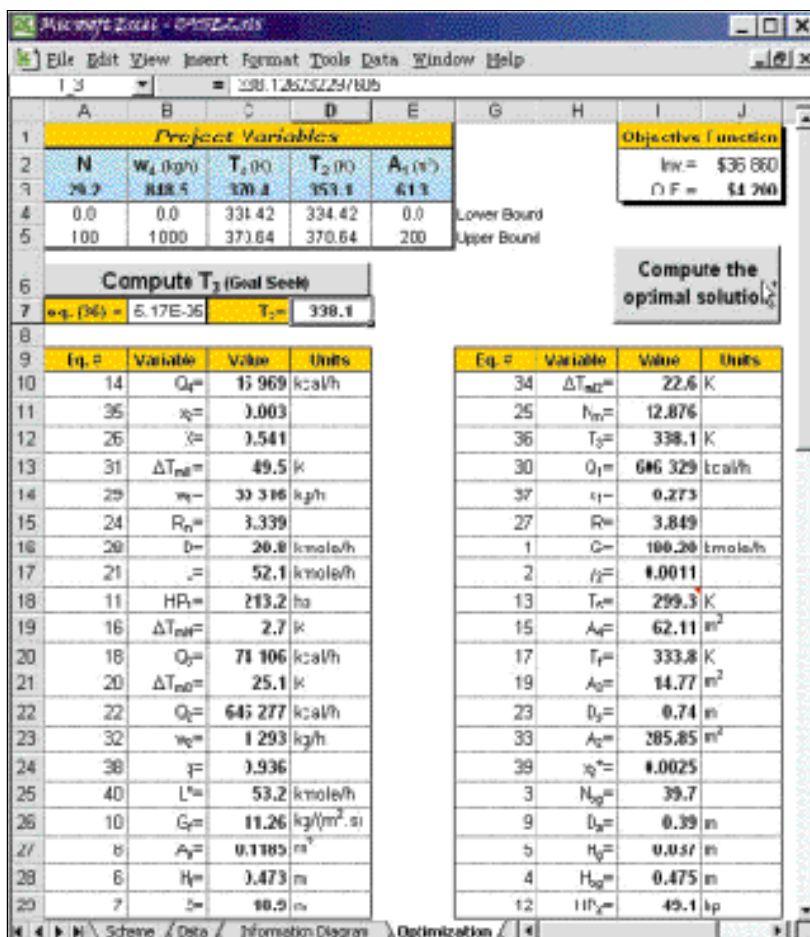


FIGURE 2. The authors created a macro to automate the iterative calculation process. Once such a macro is created, it can be assigned to a toolbar, a menu, a shortcut key, or a button, so that running the macro is as simple as clicking a button

Solver saves the day

The sequence we programmed for the order of solution is shown in Table 2. In addition to the data, there are five convenient decision variables [N , T_2 , T , W_4 , A_1], since this produces a serial solution [9]. Table 2 indicates that the first equation solved is Equation f_{36} for variable T_3 , and then Equation f_{14} for Q_4 , finishing finally with Equation f_{12} . The corresponding Fortran 77 code of this sequencing was interfaced with an adaptive, random search optimizer [10,11] for comparison with the Solver capabilities built into the Excel environment.

The Excel spreadsheet Solver function has two nonlinear optimizers: a quasi-Newton method and a Generalized Reduced-Gradient algorithm [12,13]. With them, it is possible to control the solution process by limiting the time taken and the number of interim calculations performed during the solution. It is also possible to control the precision within which constraints are binding, and the convergence criteria for the solutions.

Instead of manually invoking the Solver dialog box in the Tools menu, we have automated this task by creating a single macro. This is done by invoking the macro recorder, which saves the series of commands in the Visual Basic for Applications language [14]. Macros may then be assigned to a toolbar, menu, shortcut key, or button (Figure 2).

For this optimization, temperature T_3 — the only unknown variable from this equation — was estimated using the Excel “Goal Seek” feature to iteratively solve the nonlinear Equation f_{36} . “Goal Seek” lets the user find a specific result for one cell by adjusting the value of any other single cell. In this case, Equation f_{36} was written in the goal cell and an initial value for T_3 was assigned to another cell (Figure 3). This was also automated by creating a macro, which was assigned to a button called “Compute T_3 ”.

Excel’s workspace architecture allows one to integrate multiple datasheets in the same file. In this example, we have put together the flow-

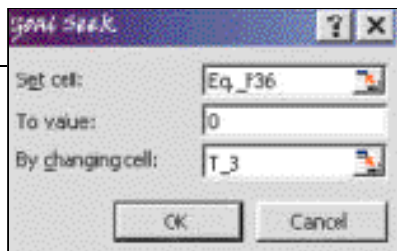


FIGURE 3. For this optimization, temperature, T_3 , was estimated using the Excel "Goal Seek" feature to iteratively solve the nonlinear Equation f_{36} —the only unknown variable from this equation. Goal Seek lets the user find a specific result for one cell by adjusting the value of any other single cell. This process was automated by creating a macro assigned to a button labeled "Compute T_3 "

sheet (Figure 1), data sheet, information matrix, algorithm, and macro module with source coding in the Visual Basic editor. Interested parties can go to www.deb.uminho.pt/ecferreira/download/abs_str.zip to download this Excel workbook file.

Results and discussion

We studied two cases (solvent recovery and air-pollution abatement). The differences pertain to the addition of a constraint for the collection efficiency of the absorption tower (in this case, $1-Gy_2/Fy_1 > 0.99$), and to the pertinent physical and economical data used during the calculations.

Case 2 (the air-pollution problem) is much more difficult to solve, since it is harder to find an initial feasible point, due to the highly constrained search space. The pertinent data for both cases are given in Table 3.

The search space for the decision variables $\{N, W_d, A_1\}$ was set quite wide, respectively $[0, 100]$, $[0, 1,000 \text{ kg/h}]$ and $[0, 200 \text{ m}^2]$, to minimize the chance of missing the global optimum. The search intervals for T_2 and T_4 were estimated from the boiling points of the pure components, giving respectively $[314.4, 350.6 \text{ K}]$ and $[334.4, 370.6 \text{ K}]$ for Cases 1 and 2.

For comparison, the MSGA algorithm [10, 11] was applied to both cases and, irrespective of the starting point, always arrived at feasible points that were very close to the global optimum. The spreadsheet was then applied to both cases, and the following conclusions reached:

1. Trial-and-error testing should be done to obtain a feasible starting point. This will avoid trapping the solver with mathematical inconsistencies, such as negative arguments of logarithmic functions, from which it

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TABLE 3. DATA

| Operating variables: | | CASE 1 | CASE 2 | Units | Physical properties: | | CASE 1 | CASE 2 | Units |
|--|-------------|-----------------------|-----------------------|-------------------|--|------------|---------|---------|--|
| Feed flowrate | $F =$ | 60 | 200 | Kmol/h | H_g parameter | $=$ | 0.51 | 0.51 | |
| Pressure | $P =$ | 760 | 760 | mmHg | H_g parameter | $=$ | 0.22 | 0.22 | |
| Composition | $y_1 =$ | 0.4 | 0.1 | | H_g parameter | $=$ | 0.00235 | 0.00235 | m^{1+d} |
| Composition | $x_3 =$ | 0.99 | 0.95 | | Empirical constant (Souders-Brown Eq.) | $K =$ | 0.10 | 0.10 | m/s |
| Temperature | $T_f =$ | 303 | 283 | K | Specific area, fillings | $a_p/3 =$ | 490 | 490 | m^2/m |
| Temperature | $T_j =$ | 293 | 278 | K | Relative volatility | $a =$ | 2 | 2 | |
| Temperature | $T_o =$ | 298 | 298 | K | Global heat transfer coefficient | $U_1 =$ | 300 | 200 | kcal/ $m^2 \cdot h \cdot K$ |
| Temperature | $T_s =$ | 393 | 393 | K | Global heat transfer coefficient | $U_2 =$ | 500 | 100 | kcal/ $m^2 \cdot h \cdot K$ |
| Reference temperature | $T_{ref} =$ | 230 | 210 | K | Global heat transfer coefficient | $U_3 =$ | 100 | 200 | kcal/ $m^2 \cdot h \cdot K$ |
| Physical properties: | | | | | Global heat transfer coefficient | $U_4 =$ | 200 | 100 | kcal/ $m^2 \cdot h \cdot K$ |
| Liquid density | $l =$ | 1,500 | 900 | kg/ m^3 | Henry's constant | $H =$ | 608 | 208 | mmHg |
| Gas density | $g =$ | 5 | 2 | kg/ m^3 | Cost factors: | | | | |
| Molar weight | $M_l =$ | 154 | 100 | kg/kmol | Feed F | $C_g =$ | 50 | 10 | $\$/h \cdot yr \cdot kg$ |
| Molar weight | $M_g =$ | 58 | 20 | kg/kmol | Product Dx_3 | $P_p =$ | 20 | 65 | $\$/h \cdot yr \cdot kg$ |
| Specific heat (streams w_1 and w_d) | $C_{pw} =$ | 1 | 1 | kcal/kg $\cdot K$ | Water | $C_w =$ | 0.0635 | 0.0635 | $\$/h \cdot yr \cdot kg$ |
| Specific heat (heat exchangers 3 & 4) | $C_p =$ | 0.2 | 0.2 | kcal/kg $\cdot K$ | Vapor (reboiler) | $C_s =$ | 35.2 | 35.2 | $\$/h \cdot yr \cdot kg$ |
| Liquid latent heat (from stripper) | $=$ | 50 | 60 | kcal/kg | Solvent | $C_l =$ | 5 | 100 | $\$/h \cdot yr \cdot kg$ |
| Water latent heat (stream w_2) | $w =$ | 500 | 500 | kcal/kg | Electricity | $C_e =$ | 89.7 | 89.7 | $\$/h \cdot yr \cdot kg$ |
| Liquid viscosity | $\mu_l =$ | 1.00×10^{-3} | 1.00×10^{-3} | kg/ $m \cdot s$ | Heat exchangers | $C_a =$ | 350 | 350 | $\$/m^2 \cdot h^{0.556}$ |
| Gas viscosity | $\mu_g =$ | 1.85×10^{-5} | 1.85×10^{-5} | kg/ $m \cdot s$ | Pumps | $C_{hp} =$ | 1,000 | 1,000 | $\$/hp^{0.30}$ |
| Liquid diffusivity | $D_l =$ | 2.0×10^{-9} | 2.0×10^{-9} | m^2/s | Absorber | $C_z =$ | 600 | 600 | $\$/m^2$ |
| Gas diffusivity | $D_g =$ | 2.2×10^{-5} | 2.2×10^{-5} | m^2/s | Stripper | $C_n =$ | 363 | 363 | $\$/N \cdot (m \text{ width})^{-1.085}$ |
| Antoine parameter | $A'_1 =$ | 32.9 | 32.9 | | Return of investment | $F_c =$ | 0.14286 | 0.08 | $\$/\$/yr$ |
| Antoine parameter | $B'_1 =$ | 14,300 | 14,300 | K | Pump characteristics: | | | | |
| Antoine parameter | $A'_2 =$ | 30.4 | 30.4 | | Pump 1 | $kp_1 =$ | 0.10 | 0.10 | hp $\cdot h/N \cdot kmol$ |
| Antoine parameter | $B'_2 =$ | 13,800 | 13,800 | K | Pump 2 | $kp_2 =$ | 0.05 | 0.05 | hp $\cdot h/(m \text{ high}) \cdot kmol$ |
| H_g parameter | $=$ | 0.557 | 0.557 | | | | | | |
| H_g parameter | $=$ | 0.32 | 0.32 | | | | | | |

cannot recover. This can be performed by changing the values of the decision variables and seeing the impact on the simulation or optimization.

2. Unfortunately, not all initial values that obey (1) will converge to the global optimum, or will converge at all.

The possible benefits of using spreadsheets to solve optimization problems include the following:

- It is easier to build a simulation or optimization problem in Excel, which

is available on many desktops, rather than coding the problem in a high-level language, or learning a new algebraic environment

- It is convenient to have a workbook in which the diagram, data, flow-sheet, occurrence matrices and simulation procedure are interconnected and easily visualized

This interconnectivity allows one to easily add new constraints and specifications during the evaluation. Phys-

ical and economic data can also be easily changed, with the effect immediately reflected. Although the Excel solver is not comparable with more-robust optimizers [10,11] or other algorithms [15], it does provide an integrated framework for problem setting, visualization, inspection and solving. ■

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Authors



Eugénio C. Ferreira is an asst. professor of biological engineering at the Univ. of Minho (Universidade do Minho, Centro de Engenharia Biológica, IBQF Campus de Gualtar, 4710-057, Braga, Portugal; Phone: +351-253-604402; E-mail: ecferrera@deb.uminho.pt). He received B.S. and Ph.D. degrees in Ch.E. from the Univ. of Porto. His expertise includes modeling and control in biochemical and wastewater processes.



Romualdo Salcedo is an associate professor of chemical engineering at the Univ. of Porto (Universidade do Porto, Departamento de Engenharia Química, Rua dos Bragas, 4050-123 Porto, Portugal; Phone: +351-22-5081644; E-mail: rsalcedo@fe.up.pt). He received a B.S. in chemical engineering from the University of Porto, and M.Eng. and Ph.D. degrees from McGill Univ. (Montreal). His expertise includes simulation and optimization of nonlinear processes, air-pollution control and statistical analysis of time series.